## 10.5 Parametric Surfaces

## 10.5.1 Graphing a Parametric Surface

Previously, parametric equations were used to describe lines. Now, we will use them to describe surfaces.

Parametric equations of one parameter produce a one-dimensional graph (curve). Parametric equations of two parameters produce a two-dimensional graph (surface). Parametric equations of n parameters produce an n-dimensional graph.

Definition

The set of all points (x, y, z) in  $\mathbb{R}^3$  such that

$$x = x(u, v)$$
  $y = y(u, v)$   $z = z(u, v)$  (1)

or

$$\mathbf{r}(u,v) = x(u,v)\mathbf{i} + y(u,v)\mathbf{j} + z(u,v)\mathbf{k}$$
(2)

where  $(u, v) \in D$ , a region in the *uv*-plane. The graph, *S*, produced by either (1) or (2) is called a **parametric surface**. The equations in (1) are called **parametric equations** of *S*. The equation (2) is called a **vector equation** for *S*. Note that the *interior* of the surface is not part of the graph.

Note: To plot a parametric surface in GeoGebra, use the command

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S = Surface(x(u,v), y(u,v), z(u,v), u, START, END, v, START, END)
```

where the first START and END represent the domain for u, and the second pair represents the domain of v.

**Example 1.** Let  $\mathbf{r}(u, v) = \left\langle \ln u, \sqrt{2v}, \frac{2}{uv} \right\rangle$ .

- (a) Determine and sketch the domain of  $\mathbf{r}$ .
- (b) Use GeoGebra to graph the surface described by  ${\bf r}.$

## 10.5.2 Parametrizing a Surface

**Example 2.** Find a parametric representation for the part of the elliptic paraboloid  $x + y^2 + 2z^2 = 4$  that lies above the plane z = 0.

**Example 3.** Let D be the cylinder  $x^2 + y^2 = 4$  with  $0 \le z \le 1$ . Find a parametrization for D.

**Example 4.** Find a parametrization for the lower half of the sphere of radius 3 centered at the origin.

## 10.5.3 Tangent Planes to Parametric Surfaces

Suppose we want to linearize a surface S, where S is defined parametrically as

$$\mathbf{r}(u,v) = \langle x(u,v), y(u,v), z(u,v) \rangle$$

Let's say our point is found when  $u = u_0$  and  $v = v_0$ . Then we have the point  $P(x_0, y_0, z_0)$ where  $x_0 = x(u_0, v_0)$ ,  $y_0 = y(u_0, v_0)$ , and  $z_0 = z(u_0, v_0)$ .

Notice

$$\mathbf{r}_{u}(u,v) = \left\langle \frac{\partial x}{\partial u}(u,v), \frac{\partial y}{\partial u}(u,v), \frac{\partial z}{\partial u}(u,v) \right\rangle \quad , \quad \mathbf{r}_{v}(u,v) = \left\langle \frac{\partial x}{\partial v}(u,v), \frac{\partial y}{\partial v}(u,v), \frac{\partial z}{\partial v}(u,v) \right\rangle$$

Then  $\mathbf{r}_u(u, v)$  and  $\mathbf{r}_v(u, v)$  are vectors on the tangent plane to S at the point determined by (u, v). Moreover, a normal vector to the tangent plane at P is

$$\mathbf{n}_{(u_0,v_0)} = \mathbf{r}_u(u_0,v_0) \times \mathbf{r}_v(u_0,v_0)$$

**Example 5.** Find the tangent plane to the parametric surface  $\mathbf{r}(u, v) = \langle u^2, v^2, uv \rangle$  when u = 1 and v = 1.